# Lecture 17: Algebraic and geometric multuplicity 

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# Lecture 17: Algebraic and Geometric Multiplicity 

1 Example - a shear in $\mathbb{R}^{2}$

2 Distinct eigenvalues

3 Determinant properties

4 Multplicity

## A shear in $\mathbb{R}^{2}$

Example (from Lecture 16) $B=\left[\begin{array}{ll}1 & 1 \\ 0 & 1\end{array}\right]$. The linear transformation $T$ described by $B$ sends $(x, y) \in \mathbb{R}^{2}$ to $(x+y, y)$. This is a horizontal shear: it shifts every point horizontally by its $y$-coordinate.
For every point $v \in \mathbb{R}^{2}, T(v)$ is on the same horizontal line as $v$. It follows that $T(v)$ is a scalar multiple of $v$ only if $v$ lies on the $X$-axis. In this case $T(v)=v$.


The characteristic polynomial of $B$ (and $T$ ) is $(\lambda-1)^{2}$.
The only eigenvalue is 1 , and it has algebraic multiplicity 2 , meaning it appears twice as a root of the characteristic polynomial.

But its geometric multiplicity is only 1 , meaning its corresponding eigenspace is 1-dimensional, just the line $y=0$.

## Repeated or distinct eigenvalues

The "shear" example shows that $\mathbb{R}^{2}$ does not have a basis consisting of eignevectors of $B=\left[\begin{array}{ll}1 & 1 \\ 0 & 1\end{array}\right]$, so $B$ is not similar to a diagonal matrix.
Also $B$ has 1 as a repeated eigenvalue (double root of its characteristic polynomial).
We will show that a matrix is diagonalizable ${ }^{1}$ if its characteristic polynomial has distinct roots.
Example $A=\left[\begin{array}{ll}-4 & 7 \\ -2 & 5\end{array}\right] \cdot \operatorname{det}(\lambda I-A)=\lambda^{2}-\lambda-6=(\lambda+2)(\lambda-3)$ :
distinct roots. Distinct eigenvalues $-2,3$.
Respective corresponding eigenvectors: $\left[\begin{array}{l}7 \\ 2\end{array}\right],\left[\begin{array}{l}1 \\ 1\end{array}\right]$.
Note these are linearly independent, so form a basis of $\mathbb{R}^{2}$.
Conclusion $P^{-1} A P=\left[\begin{array}{rr}-2 & 0 \\ 0 & 3\end{array}\right]$, where $P=\left[\begin{array}{ll}7 & 1 \\ 2 & 1\end{array}\right]$.
${ }^{1}$ Small print: possibly considered as a matrix in $M_{n}(\mathbb{C})$ if its eigenvalues are not real

## Eigenvectors for distinct eigenvalues are independent

Theorem Let $A \in M_{n}(\mathbb{R})$ and let $v_{1}, \ldots, v_{k}$ be eigenvectors of $A$ in $\mathbb{R}^{n}$, corresponding to distinct eigenvalues $\lambda_{1}, \ldots, \lambda_{k}$ of $A$. Then $\left\{v_{1}, \ldots, v_{k}\right\}$ is a linearly independent subset of $\mathbb{R}^{n}$.

Proof (for $k=3$.) First note that no two of $v_{1}, v_{2}, v_{3}$ are scalar multiples of each other, since they correspond to different eigenvalues.

Now suppose $a_{1} v_{1}+a_{2} v_{2}+a_{3} v_{3}=0$, for scalars $a_{1}, a_{2}, a_{3}$ in $\mathbb{R}$. We need to show $a_{1}=a_{2}=a_{3}=0$.
Multiplying $a_{1} v_{1}+a_{2} v_{2}+a_{3} v_{3}$ on the left by $A$, we have

$$
a_{1} A v_{1}+a_{1} A v_{2}+a_{3} A v_{3}=0 \Longrightarrow a_{1} \lambda_{1} v_{1}+a_{2} \lambda_{2} v_{2}+a_{3} \lambda_{3} v_{3}=0 .
$$

Multiply $a_{1} v_{1}+a_{2} v_{2}+a_{3} v_{3}$ by $\lambda_{1}: a_{1} \lambda_{1} v_{1}+a_{2} \lambda_{1} v_{2}+a_{3} \lambda_{1} v_{3}=0$.


Since $v_{2}$ and $v_{3}$ are linearly independent and $\lambda_{1}-\lambda_{2} \neq 0$, and $\lambda_{1}=\lambda_{3} \neq 0$, it follows that $a_{2}=a_{3}=0$, and hence that $a_{1}=0$ also.

## At most $n$ distinct eigenvalues

The following consequence of the theorem shows that a matrix cannot have too many distinct eigenvalues. We already knew this, since the eigenvalues are roots of a polynomial of degree $n$, but here we deduce it without having to appeal to any theory about polynomial equations.

Corollary Let $A \in M_{n}(\mathbb{R})$. Then $A$ has at most $n$ distinct eigenvalues in $\mathbb{R}$.

Proof If $A$ has $k$ distinct eigenvalues, with corresponding eigenvectors $v_{1}, \ldots, v_{k}$ in $\mathbb{R}^{n}$, then $k$ cannot exceed the dimension of $\mathbb{F}^{n}$, since $\left\{v_{1}, \ldots, v_{k}\right\}$ is a linearly independent set in $\mathbb{R}^{n}$. Hence $k \leq n$.
Another Corollary If $A \in M_{n}(\mathbb{R})$ has $n$ distinct eigenvalues, then $A$ is diagonalizable.

Proof A set consisting of one eigenvector for each of the $n$ eigenvalues is linearly independent and hence is a basis.

## Notes about determinants and characteristic polynomials

1 The characteristic polynomial of the square matrix $A \in M_{n}(\mathbb{R})$ is the determinant of $\lambda I_{n}-A$.
2 If $t$ is a root of this polynomial, the $t$-eigenspace of $A$ is the nullspace of the matrix $t I_{n}-A$.
3 The determinant of a diagonal or upper triangular matrix is the product of the entries on its main diagonal.
4 A square matrix is block diagonal if its non-zero entries are all contained in square blocks along its diagonal. The determinant of a block diagonal matrix is the product of the determinants of its diagonal blocks.
5 Similar matrices have the same characteristic polynomial and the same eigenvalues and eigenspace dimensions, since they represent the same linear transformation.

## Multiplicity of Eigenvalues

Let $\lambda$ be an eigenvalue of a matrix $A \in M_{n}(\mathbb{R})$. The algebraic multiplicity of $\lambda$ is the number of times that $\lambda$ occurs as a root of the characteristic polynomial. The geometric multiplicity is the dimension of the $t$-eigenspace of $A$.

Example The matrix $A=\left[\begin{array}{llll}3 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 \\ 0 & 0 & 4 & 1 \\ 0 & 0 & 0 & 4\end{array}\right]$ has two distinct eigenvalues, 3 and 4. Both have algebraic multiplicity 2 ; the characteristic polynomial is $(\lambda-3)^{3}(\lambda-4)^{2}$.
The 3-eigenspace has dimension 2, its elements are $\left[\begin{array}{l}a \\ b \\ 0 \\ 0\end{array}\right]$, for $a, b \in \mathbb{R}$. The 4-eigenspace only has dimension 1 , its elements are $\left[\begin{array}{l}0 \\ 0 \\ c \\ 0\end{array}\right]$, for $c \in \mathbb{R}$.

This $A$ is not diagonalizable since it does not have four independent eigenvectors.

## Geometric Multiplicity $\leq$ Algebraic Multiplicity

Theorem The geometric multplicity of an eigenvalue is at most equal to its algebraic multiplicity.

Proof: Suppose that $t$ has geometric multiplicity $k$ as an eigenvalue of the square matrix $A \in M_{n}(\mathbb{R})$, and let $\left\{v_{1}, \ldots, v_{k}\right\}$ be a basis for the $t$-eigenspace of $A$. Extend this to a basis $\mathcal{B}$ of $\mathbb{R}^{n}$, and let $P$ be the matrix whose columns are the elements of $\mathcal{B}$. Then the first $k$ columns of $P^{-1} A P$ have $t$ in the diagonal position and zeros elsewhere. It follows that $\lambda-t$ occurs at least $k$ times as a factor of $\operatorname{det}\left(\lambda I_{n}-P^{-1} A P\right)$, so the algebraic multiplicity of $t$ is at least $k$.

Corollary A matrix is diagonalizable if and only if the geometric multiplicity of each of its eigenvalues is equal to the algebraic multiplicity.

