

Consequences of the exchange lemma

Theorem

If V is a finite dimensional vector space over a field \mathbb{F} , then every basis of V has the same number of elements.

Proof Let B_1 and B_2 be bases of V . Then B_1 is linearly independent and B_2 is a spanning set of V , so $|B_1| \leq |B_2|$ by the Replacement Lemma. Also, B_2 is linearly independent and B_1 is a spanning set of V , so $|B_2| \leq |B_1|$ by the Replacement Lemma. Hence $|B_1| = |B_2|$.

Definition The number of elements in any (hence every) basis of a finite dimensional vector space V is called the **dimension** of V , denoted **$\dim V$** .

An Example

Let V be the space of skew-symmetric matrices in $M_3(\mathbb{R})$ (a matrix A is *skew-symmetric* if $A^T = -A$). Then

$$V = \left\{ \begin{pmatrix} 0 & a & b \\ -a & 0 & c \\ -b & -c & 0 \end{pmatrix} : a, b, c \in \mathbb{R} \right\}.$$

The typical element of V noted above can be written as

$$\begin{aligned} \begin{pmatrix} 0 & a & b \\ -a & 0 & c \\ -b & -c & 0 \end{pmatrix} &= a \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} + b \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ -1 & 0 & 0 \end{pmatrix} + c \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix} \\ &= a(E_{12} - E_{21}) + b(E_{13} - E_{31}) + c(E_{23} - E_{32}), \end{aligned}$$

where E_{ij} is the matrix with 1 in the (i, j) -position and zeros elsewhere.

We see that $\{E_{12} - E_{21}, E_{13} - E_{31}, E_{23} - E_{32}\}$ is a spanning set of V .

This set is also linearly independent. We conclude that

$\{E_{12} - E_{21}, E_{13} - E_{31}, E_{23} - E_{32}\}$ is a basis of V and that $\dim V = 3$.

More on Bases and Dimension

Recall (Steinitz Exchange Theorem) In a vector space V , if L is any linearly independent set and S is any finite spanning set, then $|L| \leq |S|$.

Let V be a vector space of dimension n over a field \mathbb{F} .

Lemma 1 Every linearly independent subset of V with n elements is a basis of V .

Lemma 2 Every spanning set of V with n elements is a basis of V .

Lemma 3 If L is a linearly independent subset of V , then L can be extended to a basis of V .

Lemma 4 If U is a proper subspace of V , then $\dim U < n$.

There is really only one \mathbb{F} -vector space of each dimension!

For any field \mathbb{F} , \mathbb{F}^n denotes the space of all column vectors with n entries.

Suppose that V is a \mathbb{F} -vector space with $\dim V = n$, and let

$B = \{v_1, \dots, v_n\}$ be a basis of V over \mathbb{F} . For every element $v \in V$, there is a unique expression for v as a linear combination of the elements of B :

$$v = a_1 v_1 + \cdots + a_n v_n$$

We refer to a_1, \dots, a_n as the **coordinates** of v with respect to the basis B . With this association, we can consider v to be represented by the column vector in \mathbb{F}^n whose entries are a_1, \dots, a_n .

This association defines a bijective correspondence between V and \mathbb{F}^n , and means that we can identify these two vector spaces as being essentially the same.

The **standard basis** of \mathbb{F}^n is $\{e_1, \dots, e_n\}$, where e_i has 1 in position i and 0 in all other positions.

Theorem Let $B = \{v_1, \dots, v_n\}$ be any set of n vectors in \mathbb{F}^n . Then B is a basis of \mathbb{F}^n if and only if the matrix A whose columns are v_1, \dots, v_n has an inverse in $M_n(\mathbb{F})$.

Proof (\Leftarrow) Suppose that A has an inverse in $M_n(\mathbb{F})$. Then $AA^{-1} = I_n$, and $Aw_1 = e_1$, where w_1 is the first column of A^{-1} . It follows that e_1 is a linear combination of v_1, \dots, v_n .

(\Rightarrow) On the other hand, suppose that B is a basis of \mathbb{F}^n . Then e_1 is a linear combination of the columns of B , and so $e_1 = Bw_1$, for some $w_1 \in \mathbb{F}^n$. Similarly $e_i = Bw_i$, for $i = 2, \dots, n$. It follows that $AW = I_n$, where W is the matrix in $M_n(\mathbb{F})$ whose columns are w_1, \dots, w_n , and hence A has an inverse in $M_n(\mathbb{F})$.

The Column Space and Row Space

Definition

Let A be a $m \times n$ matrix with entries in \mathbb{R} (or any field). The *column space* of A is the subspace of \mathbb{R}^m spanned by the columns of A . The *row space* of A is the subspace of \mathbb{R}^n spanned by the rows. The dimensions of the column space and row space are called the *column rank* and *row rank* of A .

- The row rank of a matrix is the number of linearly independent rows. It is the number of non-zero rows in a RREF obtained from the matrix.
- The column rank of a matrix is the number of linearly independent columns.

Theorem

For every matrix with entries in \mathbb{R} (or any field), the row rank and column rank are equal.

Row rank = Column Rank

Let $A \in M_{m \times n}(\mathbb{R})$. Write c and r respectively for the row rank and column rank of A .

Let C be a $m \times c$ matrix whose columns form a basis for the column space of A .

Then

$$A = CB,$$

for some $c \times n$ matrix B , since every column of A is a linear combination of the columns of C .

But now every **row** of A is a linear combination of the c rows of B .

The row space of A is contained in the rowspace of B so its dimension is at most c .

Hence $r \leq c$, and a similar argument shows that $c \leq r$.

Conclusion: $c = r$, referred to as the **rank** of A .

Themes for Chapter 3

- It is useful to be able to move between different bases for a given vector space;
- One basis may be far better than another for describing a particular linear transformation - the standard basis is not always the most useful one;
- Everything can be interpreted in terms of matrix algebra, although the setup takes some work.

Moving between two bases

Suppose we have another basis $\mathcal{B} = \{b_1, b_2, b_3\}$ of \mathbb{R}^3 (besides the standard basis $\{e_1, e_2, e_3\}$), where

$$b_1 = \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}, b_2 = \begin{bmatrix} -1 \\ -1 \\ 2 \end{bmatrix}, b_3 = \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}.$$

Question: Suppose we have some vector in \mathbb{R}^3 , for example $v = \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}$.

What are the coordinates of v with respect to \mathcal{B} ?

Another Question: Why would we want to know this?