Definition 5

Let A and B be matrices of size $m \times p$ and $p \times n$ respectively. Write v_1, \ldots, v_n for the columns of B. Then the product AB is the $m \times n$ matrices whose columns are Av_1, \ldots, Av_n .

Matrix products are often presented and explained just in terms of their individual entries.

Suppose that A is a $m \times p$ matrix and B is a $p \times n$ matrix, with entries in a field \mathbb{F} . The entry in Row *i* and Column *j* of A is denoted A_{ij} . The entry in the the (i, j) position of AB (i.e. Row *i* and Column *j*) is the *i*th entry of the vector Av_j , where the vector v_j is Column *j* of B. This is the linear combination of the *i*th entries of the columns of A (i.e. the entries of Row *i* of A, with coefficients from Column *j* of B). It is given by

$$(AB)_{ij} = A_{i1}B_{ij} + A_{i2}B_{2j} + \cdots + A_{ip}B_{pj} = \sum_{k=1}^{p} A_{ik}B_{kj}.$$

We note that the expression for $(AB)_{ij}$ above involves the scalar product of two vectors with p entries. For a field \mathbb{F} , we write \mathbb{F}^p for the vector space of all vectors with p entries from \mathbb{F} .

Definition 6

Let $u = (a_1, ..., a_p)$ and $v = (b_1, ..., b_p)$ be vectors in \mathbb{F}^p . Then the ordinary scalar product or dot product of u and v is the element of \mathbb{F} defined by

$$u \cdot v = a_1b_1 + a_2b_2 + \cdots + a_pb_p = \sum_{k=1}^p a_kb_k.$$

If $u \cdot v = 0$, we say that u and v are *orthogonal* with respect to the scalar product. If $\mathbb{F} = \mathbb{R}$, this means that the vectors u and v are perpendicular in Euclidean space.

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If A is $m \times p$ with rows u_1, \ldots, u_m , and B is $p \times n$ with columns v_1, \ldots, v_n , then the product AB is a table of values of scalar products of Rows of A with Columns of B.

$$AB = \begin{pmatrix} u_1 \cdot v_1 & u_1 \cdot v_2 & \dots & u_1 \cdot v_n \\ u_2 \cdot v_1 & u_2 \cdot v_2 & \dots & u_2 \cdot v_n \\ \vdots & \vdots & & \vdots \\ u_m \cdot v_1 & u_m \cdot v_2 & \dots & u_m \cdot v_n \end{pmatrix}$$

Example Let A be the 3×3 matrix formed by the table that gives the numbers of first year Humanities (H), Engineering (E) and Science (S) students in first year at Eigen University, in 2015, 2016 and 2017.

	H	Е	S		100	70
2015	50	100	70) 200	20 20
2016	60	80	80	$A = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$	J 00 J 70	00 70
2017	80	70	70		J 70	10

Every fiirst year student at Eigen University takes either Linear Algebra (LA) or Calculus (C) or both. The table below shows the numbers of ECTS credits completed annually in each, by students in each of the three subject areas.

Now look at the meaning of the entries of the product AB.

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Linear transformations are the primary functions between vector spaces that are of interest in linear algebra. For now we will stick to linear transformations between spaces of real column vectors.

Definition 7

Let *m* and *n* be positive integers. A linear tranformation T from \mathbb{R}^n to \mathbb{R}^m is a function $T : \mathbb{R}^n \to \mathbb{R}^m$ that satisfies

•
$$T(u + v) = T(u) + T(v)$$
, and

•
$$T(\lambda v) = \lambda T(v)$$
,

for all u and v in \mathbb{R}^n , and all scalars $\lambda \in \mathbb{R}$.

The Matrix of a Linear Transformation

Suppose that $T : \mathbb{R}^3 \to \mathbb{R}^2$ is a linear transformation. Then we can calculate the image under T of any vector $\begin{pmatrix} a \\ b \\ c \end{pmatrix}$, if we know the images under T of the standard basis vectors $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$, $\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$ and $\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$. From the definition, we have

$$T\left(\begin{array}{c}a\\b\\c\end{array}\right) = aT\left(\begin{array}{c}1\\0\\0\end{array}\right) + bT\left(\begin{array}{c}0\\1\\0\end{array}\right) + cT\left(\begin{array}{c}0\\0\\1\end{array}\right) = A\left(\begin{array}{c}a\\b\\c\end{array}\right),$$

where A is the 2×3 matrix that has the images of the three standard basis vectors as its three columns.

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